

Your Next Intelligent **Move**



iPOS8010 BX-CAN INTELLIGENT SERVO DRIVE 10A, 80VDC

For Brushless, Brushed, Linear or Step Motors

DESCRIPTION

The iPOS8010 BX-CAN is a new member of the iPOS family of Technosoft intelligent drives. It is based on a new design concept for closed-frames drives, offering a very compact and cost effective solution for the control of rotary or linear brushless, DC brush, and step motors of powers up to 800 W.

Designed to cover low to medium volume applications, the iPOS8010 BX-CAN embeds motion controller, drive, and PLC functionalities into a single unit.

When used as an intelligent drive like all other members of the iPOS family - the iPOS8010 BX-CAN is empowered by the extreme flexibility offered by the TML (Technosoft Motion Language) instruction set. The unit can replace a host in various single or multi-axis stand-alone applications.

Advanced positioning profiles like the PVT or electronic caming, I/O and program flow control, data transfer between axes, subrou-tines, ISRs and multiple homing modes ease the motion application implementation task.

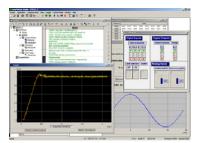
In systems that require a host, the iPOS operates as an intelligent slave executing motion sequences triggered via commands received on RS-232 or CAN while fully supporting as well the CiA402 CANopen drive profile.

DUAL LOOP

Equipped with 2 feedback connectors, the iPOS8010 BX-CAN provides advanced dual-loop control schemes that minimize the transmission backlash negative effects.

EASYMOTION STUDIO

The configuration, tuning and programming of the iPOS8010 BX-CAN drive is easy with Technosoft's powerful graphical platform, Easy-Motion Studio.



P091.029.iPOS8010 BX-CAN.LFT.0820



FEATURES :

- Motion controller and drive in a single compact unit
- Universal solution for control of rotary and linear brushless, brushed and 2 or 3-phase step motors
- Advanced motion control capabilities (PVT, S-curve, elec tronic cam)

Motor supply: 11-80V; Logic SELV/ PELV supply: 9-36V; STO SELV/PELV supply: 18-36V

 Motion programming via TML (Technosoft Motion Language) or motion libraries for Visual C / VB/LabVIEW / Linux and PLC

- Communication :
 - RS-232 serial

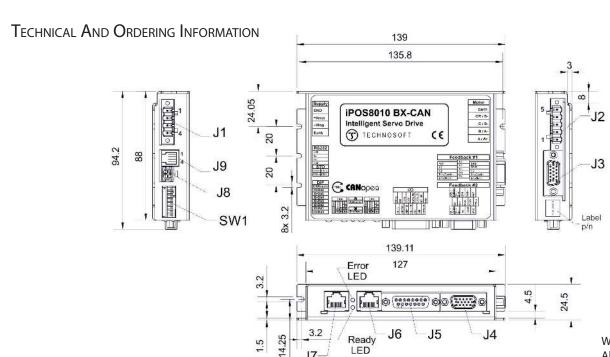
- CAN-Bus with TMLCAN or CANopen (CiA301, 305, 402) protocols

- Digital and analogue I/Os:
 - 4 PNP/NPN digital programmable inputs, 24 V
 - 4 NPN digital outputs, 5 36 V, 0.5 A
 - 2 analogue inputs: 12 bit resolution, 0 5 V
- Safety:
 - 2 Safe Torque Off inputs (STO)
- Feedback devices (dual-loop supported) : 1stFeedback :
 - Incremental quad encoder (differential)
 - Analogue sine/cosine encoder (differential 1Vpp)
 - Digital Hall sensors
 - 2nd Feedback :
 - Incremental quad encoder (differential)
- Protections :
 - Over-current, over-temperature, short circuit
 - Over and undervoltage, i2t, control error

ELECTRICAL SPECIFICATIONS

Motor power supply:	12 - 80 VDC
Logic supply :	12 - 36 Vdc
STO supply :	12 - 36 Vdc
Continuous phase current	10A
Peak current (10 sec. max.)	20 A
PWM switching frequency	20 - 60 kHz
Ambient operating temperature	0 °C - 40 °C

This information is subject to change without notice.



Weight : 240 g All dimensions are in mm.

+ Global tolerance [mm] 0.1

All dimensions are in mm. Drawings not to scale.

J1 Motor Supply	J3 Primary	J4 Secondary	J5 Digital, analog,	J6&J7 CANopen	LED1
1 GND	Feedback #1	Feedback #2	I/O and logic supply	1 Can-Hi	Green = Ready
2 +VMOT	1 +5VOUT	1+5VOUT	1 GND	2 Can-Lo	Red = Error
3 +VLOG	2 Hall 1	2 Data+/SL+	2 IN2/LSP	3 GND	
4 Earth	3 Hall 2	3 Data-/SL-	3 OUT2/Error	4 ,5 -	SW1
	4 B1+/Cos+	4 B2+/Dir+	4 OUT3/Ready	68 n.c	1: ON = CANopen
J2 Motor Output 1 A/A+ 2 B/A- 3 C/B+	5 A1+/Sin1+	5 A2+/Pulse+	5 OUT0	J8 Safe Torque Off	OFF = TMLCAN
	6 n.c.	6 +VLOG	6 OUT1		2: Axis ID - Bit 6
	7 n.c.	7 CLK+/MA+	7 +5VOUT	2 STO2+	3: Axis ID - Bit 5 4: Axis ID - Bit 4
	8 n.c.	8 CLK-/MA-	8 +VLOG	2 STO2+ 3 STO1-	
4 CR/B-	9 Z1+	9 Z2+	9 IN3/LSN	4 STO2-	5: Axis ID - Bit 3
5 Earth	10 Z1-	10 Z2-	10 IN0		6: Axis ID - Bit 2
	11 GND	11 GND	11 IN1	J9 RS232	7: Axis ID - Bit 1
	12 Temp Mot	12 FDBK	12 REF10+	1 GND	
	13 Hall 3	13 n.c.	13 REF10-	2 232TX	8: Axis ID - Bit 0
	14 B1-/Cos-	14 B2-/Dir-	14 REFSEL	3 232RX	
	15 A1-/Sin-	15 A2-/Pulse-	15 REF5	4 GND	

ORDERING INFORMATION

The high level graphical deve- lopment environment EasyMotion Studio supports the configuration, parameterization and programming of the drive, through:

- Motion system set-up wizard
- Tuning assistance with capture functions
- Definition, programming and testing of motion sequences

MOTION CONTROL LIBRARIES

The TML_LIB Motion Control Libraries can be used to implement a motion control application on a PC from Visual C / C++, C#, Visual Basic, Delphi or LabVIEW under Windows or Linux operating systems. If a PLC is used as host, implementa-

tions of the TML_LIB according with IEC-61131 stand-ard are available for Siemens, B&R and Omron PLCs.

Application notes with TML program examples at : <u>www.technosoftmotion.com</u>

P034.001.E002	EasyMotion Studio Software
P040.001.Exxx	TML_LIB Motion Library*
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iPOS8010 BX-CAN, 80V,10A, cl. frame, Enc. CAN

*ask for existing libraries types

FLEXIBILITY :

P029.025.E201

Control schemes supported by the iPOS8010 BX-CAN Drive

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Motor types	Torque Control	Speed Control	Position Control**
Brushless	\checkmark	\checkmark	\checkmark
Brushed	\checkmark	\checkmark	\checkmark
Step		\checkmark	\checkmark
Linear	\checkmark	\checkmark	\checkmark
		** Dual-loop	control supported

CONNECTORS TYPE AND MATING CONNECTORS :

Connector	Mating connectors
J1	CTBA9208/4FL CAMDEN
J2	CTBA9208/5FL CAMDEN
J3, J4	Generic 15-pin HighDensity D-Sub male
J5	Generic 15-pin D-Submale, DB15
J6,J7	-
8L	Molex 43045-0400/ 43030-0007
J9	Generic RJ10-4/4 phone plug

SALES OFFICES

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