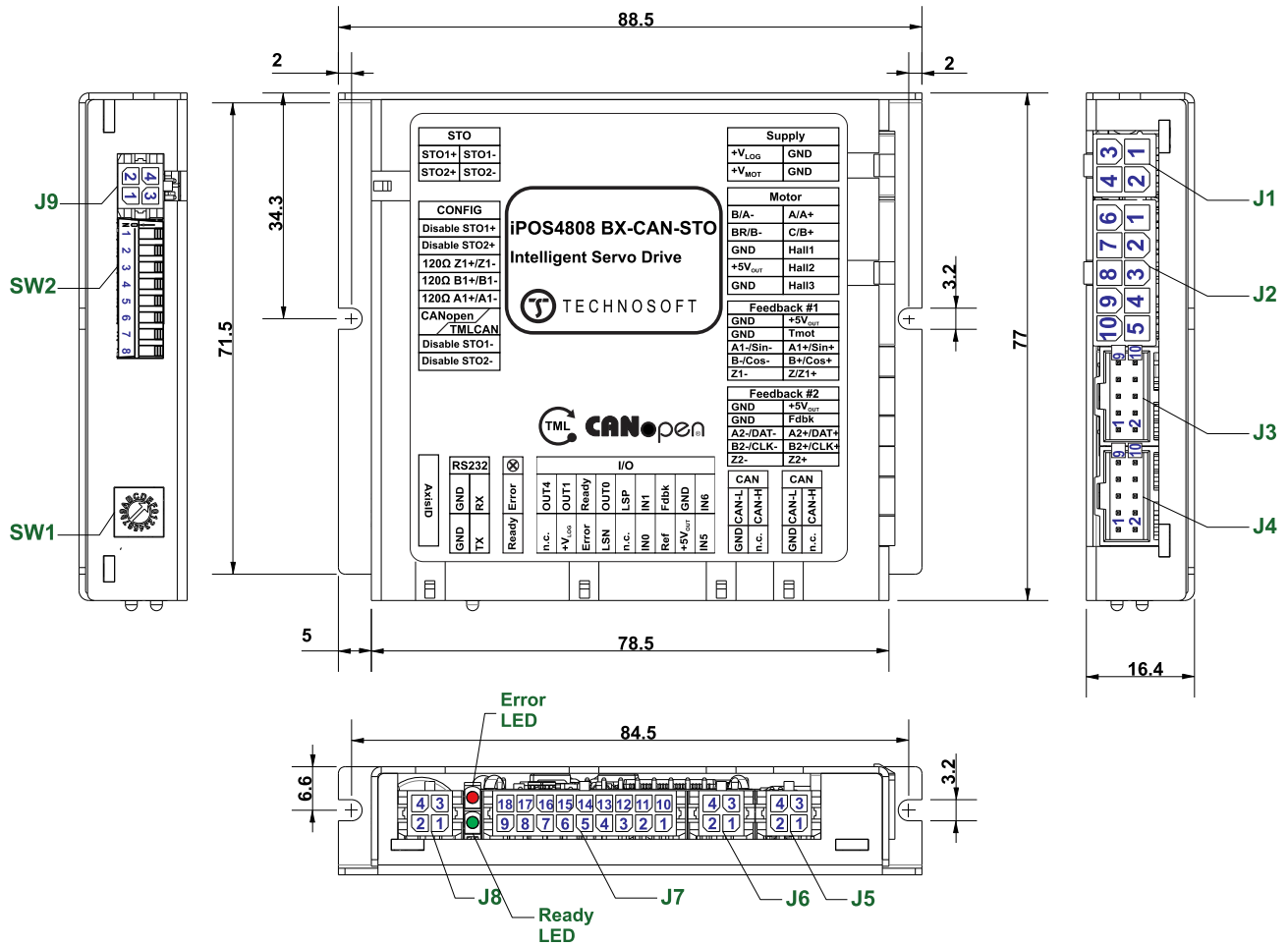




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All dimensions are in mm; Drawing not to scale.

Motor – sensor configurations					
Sensor	Motor				
	PMSM	BLDC	DC BRUSH	STEP (2-ph)	STEP ² (3-ph)
Incr. Encoder	✔		✔	✔	✔
Incr. Encoder + Hall	✔	✔			
Analog Sin/Cos	✔	✔	✔	✔	✔
SSI	✔	✔	✔	✔	✔
BiSS-C	✔	✔	✔	✔	✔
EnDAT ¹	✔	✔	✔	✔	✔
Linear Halls ³	✔				
Tacho			✔		
Open-loop (no sensor)				✔	✔

¹ Available starting with F514K firmware version

² Sensor used only for step loss detection

³ For more details, please contact Technosoft

Features

- Motion controller and drive in a single compact unit based on MotionChip™ technology
- Universal solution for control of rotary and linear brushless, brushed and 2 or 3-phase step motors
- Advanced motion control capabilities (PVT, S-curve, electronic cam)
- Motor supply: 11-50V. Logic supply: 9-36V
- Output current: 8A cont. (BLDC mode); 20A_{PEAK}, up to 100KHz PWM
- STO: 2 safe torque-off inputs, safety integrity level (SIL3/Cat3/PLe) acc. to EN61800-5-1; -2/ EN61508-3; -4/ EN ISO 13849-1.

- Feedback Devices (dual-loop support)
- 1st feedback devices supported:
 - Incremental encoder interface (single ended or differential)
 - pulse & direction interface (single ended) for external (master) digital reference
 - Analogue sin/cos encoder interface (differential 1V_{pp})
 - Digital Hall sensor interface (single-ended and open collector)
- 2nd feedback devices supported:
 - Incremental encoder interface (differential)
 - pulse & direction interface (differential) for external (master) digital reference
 - SSI/BISS-C/EnDAT¹ encoder interface
- 6 digital inputs, 12-36V, PNP/NPN programmable: 2 for limit switches, 4 general-purpose
- 5 digital outputs, 5-36V, 0.5A, NPN open-collector: Ready, Error, 3 general-purpose
- 2 analogue inputs: 12-bit, 0-5V: Reference, Feedback or general purpose
- RS-232 serial & CAN-bus 2.0B interfaces
- 16 h/w addresses selectable by h/w rotative hex switch
- TMLCAN and CANopen (CiA 301v4.2 and 402v3.0) protocols selectable by h/w switch
- 16k x 16 SRAM memory for data acquisition
- 16k x 16 E²ROM to store setup data, TML motion programs, cam tables and other user data
- Operating ambient temperature: 0-40°C (over 40°C with derating)
- NTC/PTC analogue Motor Temperature sensor input
- Firmware: F514+

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Mating Connectors				
Producer	Part No.	Connector	Description	Wire Gauge
MOLEX	39-03-9042	J1	MINIFIT JR. receptacle housing, 2x2 way	AWG 18...20
MOLEX	39-03-9102	J2	MINIFIT JR. receptacle housing, 2x5 way	AWG 18...20
MOLEX	45750-1111	J1, J2	CRIMP PIN, MINIFIT JR., 13A	AWG 18...20
MOLEX	90142-0010	J3, J4	C-Grid III™ Crimp Housing Dual Row, 10 Circuits, with retention	AWG 22...24
	90143-0010		C-Grid III™ Crimp Housing Dual Row, 10 Circuits, without retention	
MOLEX	90119-0109	J3, J4	C-Grid III™ Crimp Terminal	AWG 22...24
MOLEX	43025-1800	J7	MICROFIT RECEPTACLE HOUSING, 2x9 WAY	AWG 20...24
MOLEX	43025-0400	J5, J6, J8, J9	MICROFIT RECEPTACLE HOUSING, 2x2 WAY	AWG 20...24
MOLEX	43030-0007	J5, J6, J7, J8, J9	CRIMP PIN, MICROFIT, 5A	AWG 20...24

Pin	Name	Type	Description
1	Z2-	I	Incr. encoder2 Z- diff. input; has 120Ω resistor between pins 1 and 2
2	Z2+	I	Incr. encoder2 Z+ diff. input; has 120Ω resistor between pins 1 and 2
3	B2-/Dir-/CLK-/MA-	I/O	Incr. encoder2 B- diff. input, or Dir-, or Clock- for SSI & EnDAT, or Master- for BiSS; has 120Ω resistor between pins 3 and 4
4	B2+/Dir+/CLK+/MA+	I/O	Incr. encoder2 B+ diff. input, or Dir+, or Clock+ for SSI & EnDAT, or Master+ for BiSS; has 120Ω resistor between pins 3 and 4
J4 5	A2-/Pulse-/Data-/SL-	I	Incr. encoder2 A- diff. input, or Pulse-, or Data- for SSI & EnDAT, or Slave- for BiSS; has 120Ω resistor between pins 5 and 6
6	A2+/Pulse+/Data+/SL+	I	Incr. encoder2 A+ diff. input, or Pulse+, or Data+ for SSI & EnDAT, or Slave+ for BiSS; has 120Ω resistor between pins 5 and 6
7	GND	-	Return ground for sensors supply
8	FDBK	I	Analogue input, 12-bit, 0-5V. Used to read an analogue position or speed feedback (as tach), or used as general purpose analogue input. Also connected to J7 pin12.
9	GND	-	Return ground for sensors supply
10	+5V _{OUT}	O	5V output supply for sensors usage

Pin	Name	Type	Description
J5 & J6 1	n.c.	-	J5 pin1 is internally connected only to J6 pin1.
2	GND	-	Return ground for RS-232 pins
3	CAN Hi	I/O	CAN-Bus positive line(dominant high)
4	CAN Lo	I/O	CAN-Bus negative line (dominant low)


Pin	Name	Type	Description
1	IN5	I	12-36V general-purpose digital PNP/NPN input
2	+5V _{OUT}	O	5V output supply for I/O usage
3	REF	I	Analogue input, 12-bit, 0-5V. Used to read an analog position, speed or torque reference, or used as general purpose analogue input
4	IN0	I	12-36V general-purpose digital PNP/NPN input
5	n.c.	-	not connected
6	IN3/LSN	I	12-36V digital PNP/NPN input. Negative limit switch input
7	OUT2/Error	O	12-36V 0.5A, drive Error output, active low, NPN open-collector/TTL pull-up. Also drives the red Error LED.
8	+V _{Log}	I	Positive terminal of the logic supply: 9 to 36V _{DC} . Also internally connected to J1 pin 3.
9	n.c.	-	not connected
J7 10	IN6	I	12-36V general-purpose digital PNP/NPN input
11	GND	-	Return ground for I/O pins
12	FDBK	I	Analogue input, 12-bit, 0-5V. Used to read an analogue position or speed feedback (as tach), or used as general purpose analogue input; Connected also to J4 pin 8.
13	IN1	I	12-36V general-purpose digital PNP/NPN input
14	IN2/LSP	I	12-36V digital PNP/NPN input. Positive limit switch input
15	OUT0	O	5-36V 0.5A, general-purpose digital output, NPN open-collector/TTL pull-up
16	OUT3/Ready	O	5-36V 0.5A, drive Ready output, active low, NPN open-collector/TTL pull-up. Also drives the green Ready LED.
17	OUT1	O	5-36V 0.5A, general-purpose digital output, NPN open-collector/TTL pull-up
18	OUT4	O	5-36V 0.5A, general-purpose digital output, NPN open-collector/TTL pull-up

Connectors Description

Pin	Name	Type	Description
J1 1	GND	-	Negative return (ground) of the power supply
2	GND	-	Negative return (ground) of the power supply
J1 3	+V _{Log}	I	Positive terminal of the logic supply input: 9 to 36V _{DC}
4	+V _{MOT}	I	Positive terminal of the motor supply: 11 to 50V _{DC} .

Pin	Name	Type	Description
J2 1	A/A+	O	Phase A for 3-ph motors, A+ for 2-ph steppers, Motor+ for DC brush motors
2	C/B+	O	Phase C for 3-ph motors, B+ for 2-ph steppers
3	Hall 1	I	Digital input Hall 1 sensor
4	Hall 2	I	Digital input Hall 2 sensor
J2 5	Hall 3	I	Digital input Hall 3 sensor
6	B/A-	O	Phase B for 3-ph motors, A- for 2-ph steppers, Motor- for DC brush motors
7	BR/B-	O	Brake resistor / Phase B- for step motors
8	GND	-	Negative return (ground) of the motor supply
9	+5V _{OUT}	O	5V output supply - internally generated
10	GND	-	Negative return (ground) of the motor supply

Pin	Name	Type	Description
J3 1	Z1-	I	Incr. encoder1 Z- diff. input
2	Z1+	I	Incr. encoder1 Z single-ended, or Z+ diff. input
3	B1-/Cos-	I	Incr. encoder1 B- diff. input, or analogue encoder Cos- diff. input
4	B1+/Cos+/Dir	I	Incr. encoder1 B single-ended, or B+ diff. input, or Dir, or analogue encoder Cos+ diff. input
J3 5	A1-/Sin-	I	Incr. encoder1 A- diff. input, or analogue encoder Sin- diff. input
6	A1+/Sin+/Pulse	I	Incr. encoder1 A single-ended, or A+ diff. input, or Pulse, or analogue encoder Sin+ diff. input
7	GND	-	Return ground for sensors supply
8	Temp Mot	I	NTC/PTC input. Used to read an analog temperature value
9	GND	-	Return ground for sensors supply
10	+5V _{OUT}	O	5V output supply for I/O usage

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Pin	Name	Type	Description
1	232TX	O	RS-232 Data Transmission
2	GND	-	Return ground for RS-232 pins
3	232RX	I	RS-232 Data Reception
4	GND	-	Return ground for RS-232 pins

Pin	Name	Type	Description
1	STO2+	I	Safe Torque Off input 2, positive input (opto-isolated, 18÷40V)
2	STO1+	I	Safe Torque Off input 1, positive input (opto-isolated, 18÷40V)
3	STO2-	I	Safe Torque Off input 2, negative return(opto-isolated, 18÷40V)
4	STO1-	I	Safe Torque Off input 1, negative return(opto-isolated, 18÷40V)

Switch	Position	Description
SW1	0..F	H/W Axis ID = 1 to 15 when switch is 1 to F Exception: SW1 = 0 -->Axis ID = 255.

Pin	Position	Description
1	down(ON)	Disable STO1+ function. Connects internally +V _{LOG} to STO1+
2	down(ON)	Disable STO2+ function. Connects internally +V _{LOG} to STO2+
3	down(ON)	Connect an 120Ω resistor between Z1+ and Z1- feedback pins
4	down(ON)	Connect an 120Ω resistor between B1+ and B1- feedback pins
5	down(ON)	Connect an 120Ω resistor between A1+ and A1- feedback pins
6	down(ON)	Select CANopen communication protocol
	up(OFF)	Select TMLCAN communication protocol
7	down(ON)	Disable STO1- function. Connects internally GND to STO1-
8	down(ON)	Disable STO2- function. Connects internally GND to STO2-

Electrical characteristics

All parameters measured under the following conditions (unless otherwise specified):

- V_{LOG} = 24 VDC; V_{MOT} = 48VDC
- Supplies start-up / shutdown sequence: -any-
- Load current (sinusoidal amplitude / continuous BLDC, DC, stepper) = 8A

Operating Conditions		Min.	Typ.	Max.	Units
Ambient temperature		0		40 ^{1,3}	°C
Ambient humidity	Non-condensing	0		90	%Rh
Altitude / pressure ²	Altitude (vs. sea level)	-0.1	0 ÷ 2.5	²	Km
	Ambient Pressure	0 ²	0.75 ÷ 1	10.0	atm
Storage Conditions		Min.	Typ.	Max.	Units
Ambient temperature		-40		105	°C
Ambient humidity	Non-condensing	0		100	%Rh
Ambient Pressure		0		10.0	atm
ESD capability (Human body model)	Not powered; applies to any accessible part			±0.5	kV
	Original packaging			±15	kV
Mechanical Mounting		Min.	Typ.	Max.	Units
Airflow	natural convection ³ , closed box				
Environmental Characteristics		Min.	Typ.	Max.	Units
Size (Length x Width x Height)	Without mating connectors	88.5 x 77 x 16.4			mm
	With recommended mating connectors.	~3.48 x 3.03 x 0.65			inch
		98 x 85 x 19.5			mm
		~3.86 x 3.35 x 0.77			inch
Weight	Without mating connectors	110			g
Power dissipation	Idle (no load)	1.7			W
	Operating	4.3			W
Efficiency		98			%
Cleaning agents	Dry cleaning is recommended	Only Water- or Alcohol- based			
Protection degree	According to IEC60529, UL508	IP20			-

Logic Supply Input (+V _{LOG})		Min.	Typ.	Max.	Units
Supply voltage	Nominal values	9		36	V _{DC}
	Absolute maximum values, drive operating but outside guaranteed parameters	8		40	V _{DC}
	Absolute maximum values, continuous	-0.6		42	V _{DC}
	Absolute maximum values, surge (duration ≤ 10ms) [†]	-1		+45	V
Supply current	+V _{LOG} = 12V		130		mA
	+V _{LOG} = 24V		90	280	
	+V _{LOG} = 40V		85		

Motor Supply Input (+V _{MOT})		Min.	Typ.	Max.	Units
Supply voltage	Nominal values	11		50	V _{DC}
	Absolute maximum values, drive operating but outside guaranteed parameters	9		52	V _{DC}
	Absolute maximum values, continuous	-0.6		54	V _{DC}
	Absolute maximum values, surge (duration ≤ 10ms) [†]	-1		57	V
Supply current	Idle		1	5	mA
	Operating	-20	±8	+20	
	Absolute maximum value, short-circuit condition (duration ≤ 10ms) [†]			26	

Motor Outputs (A/A+, B/A-, C/B+, BR/B-)		Min.	Typ.	Max.	Units
Nominal output current, continuous ⁴	for DC brushed, steppers and BLDC motors with Hall-based trapezoidal control			8	A
	for PMSM motors with FOC sinusoidal control (sinusoidal amplitude value)			8	
	for PMSM motors with FOC sinusoidal control (sinusoidal effective value)			5.66	
Motor output current, peak	maximum 2.5s	-20		+20	A
Short-circuit protection threshold		±22	±26	±30	A
Short-circuit protection delay		5	10		µs
On-state voltage drop	Nominal output current; including typical mating connector contact resistance		±0.3	±0.5	V
Off-state leakage current			±0.5	±1	mA

Motor inductance (phase-to-phase)	Recommended value, for current ripple max. ±5% of full range; +V _{MOT} = 36 V	F _{PWM}			µH
		20 kHz	330		
		40 kHz	150		
		60 kHz	120		
		80 kHz	80		
		100 kHz	60		
Motor inductance (phase-to-phase)	Minimum value, limited by short-circuit protection; +V _{MOT} = 36 V	20 kHz	120		µH
		60 kHz	40		
		40 kHz	30		
		80 kHz	15		
		100 kHz	8		
		100 kHz	8		
Motor electrical time-constant (L/R)	Recommended value for ±5% current measurement error	20 kHz	250		µs
		40 kHz	125		
		60 kHz	100		
		80 kHz	63		
		100 kHz	50		
Current measurement	FS = Full Scale accuracy		±4	±8	%FS

Supply Output (+5V)		Min.	Typ.	Max.	Units
Output voltage	Current sourced = 250mA	4.8	5	5.2	V
Output current		600	650		mA
Short-circuit		NOT protected			
Over-voltage		NOT protected			
ESD protection	Human body model	±1			kV
RS-232		Min.	Typ.	Max.	Units
Compliance		TIA/EIA-232-C			
Bit rate	Software selectable	9600		115200	Baud
Short-circuit	232TX short to GND	Guaranteed			
ESD protection	Human body model	±2			kV

¹ Operating temperature at higher temperatures is possible with reduced current and power ratings

² iPOS4808 can be operated in vacuum (no altitude restriction), but at altitudes over 2,500m, current and power rating are reduced due to thermal dissipation efficiency.

³ In case of forced cooling (conduction or ventilation) the maximum ambient temperature can be increased substantially.

⁴ @20KHz F_{PWM}

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Digital Inputs (IN0, IN1, IN2/LSP, IN3/LSN, IN5, IN6) ¹		Min.	Typ.	Max.	Units	
Mode compliance		PNP				
Default state		Logic LOW				
Input voltage	Logic "LOW"	-36	0	2.4	V	
	Logic "HIGH"	7.5	24	36		
	Hysteresis	1.2	2.4	2.8		
	Floating voltage (not connected)		0			
	Absolute maximum, continuous	-36		+39		
Input current	Absolute maximum, surge (duration ≤ 1S) [†]	-50		+50	mA	
	Logic "LOW"; pulled to GND		0			
Logic "HIGH"; pulled to +24V			8	10		
Mode compliance		NPN				
Default state		Logic HIGH				
Input voltage	Logic "LOW"		0	1.6	V	
	Logic "HIGH"	1.8	24	39		
	Hysteresis	1.2	2.4	2.8		
	Floating voltage (not connected)		15			
	Absolute maximum, continuous	-10		+39		
Input current	Absolute maximum, surge (duration ≤ 1S) [†]	-20		+40	mA	
	Logic "LOW"; Pulled to GND		8	10		
Logic "HIGH"; Internal 12KΩ pull-up to +Vlog		0	0	0		
Input frequency		0		10	kHz	
Minimum pulse		6			μs	
ESD protection	Human body model	±5			kV	
Digital Outputs (OUT0, OUT1, OUT2/Error, OUT3/Ready, OUT4)		Min.	Typ.	Max.	Units	
Mode compliance		TTL / open-collector / NPN 24V				
Default state		High-Z (floating)				
Input voltage	Not supplied (+V _{LOG} floating or to GND)	High-Z (floating)				
	Immediately after power-up	OUT0, OUT1, OUT4		Logic "HIGH"		
	Normal operation	OUT2/Error, OUT3/Ready		Logic "LOW"		
Output voltage	Normal operation	OUT0, OUT1, OUT2/Error, OUT3/Ready		Logic "HIGH"		
	Logic "LOW"; output current = 0.5A			0.8	V	
	Logic "HIGH"; output current = 0, no load	2.9	3	3.3		
	Logic "HIGH"; external load to +V _{LOG}	4	4.5	5		
	Absolute maximum, continuous	-0.5		V _{LOG} +0.5		
Absolute maximum, surge (duration ≤ 1S) [†]	-1		V _{LOG} +1			
Output current	Logic "LOW", sink current			0.5	A	
	Logic "LOW", sink current, pulse ≤ 5 sec.			1	A	
	Logic "HIGH", source current; external load to GND; V _{OUT} ≥ 2.0V	OUT2/Error, OUT3/Ready		2		mA
		OUT0, OUT1, OUT4		4		mA
	Logic "HIGH", leakage current; external load to +V _{LOG} ; V _{OUT} = V _{LOG} max = 40V		0.1	0.2	mA	
Minimum pulse width		2			μs	
ESD protection	Human body model	±15			kV	

Digital Hall Inputs (Hall1, Hall2, Hall3)		Min.	Typ.	Max.	Units
Mode compliance		TTL / CMOS / Open-collector			
Default state		Logic HIGH			
Input voltage	Input floating (wiring disconnected)		0	0.8	V
	Logic "LOW"				
	Logic "HIGH"	2	5		
	Floating voltage (not connected)		4.4		
Input current	Absolute maximum, surge (duration ≤ 1S) [†]	-10		+15	mA
	Logic "LOW"; Pull to GND		0	5	
Logic "HIGH"; Internal 1KΩ pull-up to +5V		0	0	0	
Minimum pulse width		2			μs
ESD protection	Human body model	±5			kV
Encoder1 Inputs (A1/A1+, A1-, B1/B1+, B1-, Z1/Z1+, Z1-)		Min.	Typ.	Max.	Units
Single-ended mode compliance		TTL / CMOS / Open-collector			
Leave negative inputs disconnected		Logic HIGH			
Input voltage, single-ended mode A/A+, B/B+	Logic "LOW"			1.6	V
	Logic "HIGH"	1.8			
	Floating voltage (not connected)		3.3		
Input voltage, single-ended mode Z/Z+	Logic "LOW"			1.2	V
	Logic "HIGH"	1.4			
	Floating voltage (not connected)		4.7		
Input current, single-ended mode A/A+, B/B+, Z/Z+	Logic "LOW"; Pull to GND		5.5	6	mA
	Logic "HIGH"; Internal 2.2KΩ pull-up to +5	0	0	0	
Differential mode compliance	For full RS422 compliance, see ²	TIA/EIA-422-A			
Input voltage, differential mode	Hysteresis	±0.06	±0.1	±0.2	V
	Common-mode range (A+ to GND, etc.)	-7		+7	
Input impedance, differential	A1+ to A1-, B1+ to B1- Z1+ to Z1-		1		kΩ
Input frequency	Single-ended mode, Open-collector / NPN	0		5	MHz
	Differential mode, or Single-ended driven by push-pull (TTL / CMOS)	0		10	MHz
Minimum pulse width	Single-ended mode, Open-collector / NPN	1			μs
	Differential mode, or Single-ended driven by push-pull (TTL / CMOS)	50			ns
Input voltage, any pin to GND	Absolute maximum values, continuous	-7		+7	V
	Absolute maximum, surge (duration ≤ 1S) [†]	-11		+14	
ESD protection	Human body model	±1			kV
Encoder2 Inputs (A2+/Data+, A2-/Data-, B2+/Clk+, B2-/Clk-, Z2+, Z2-) ³		Min.	Typ.	Max.	Units
Differential mode compliance		TIA/EIA-422-A			
Input voltage	Hysteresis	±0.06	±0.1	±0.2	V
	Differential mode	-14		+14	
	Common-mode range (A+ to GND, etc.)	-11		+14	
Input impedance, differential	A2+, B2+, Z2+ A2-, B2-, Z2-		120		Ω
Input frequency	Differential mode	0		10	MHz
Minimum pulse width	Differential mode	50			ns

¹ The digital inputs are software selectable as PNP or NPN

² For full RS-422 compliance, 120Ω termination resistors must be connected across the differential pairs, set SW2 pins 3, 4 and 5 to ON.

³ Encoder2 differential input pins have internal 120Ω termination resistors connected across

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Sin-Cos Encoder Inputs (Sin+, Sin-, Cos+, Cos-)		Min.	Typ.	Max.	Units
Input voltage, differential	Sin+ to Sin-, Cos+ to Cos-		1	1.25	V _{PP}
Input voltage, any pin to GND	Operational range	-1	2.5	4	V
	Absolute maximum values, continuous	-7		+7	
	Absolute maximum, surge (duration ≤ 1s) [†]	-11		+14	
Input impedance	Differential, Sin+ to Sin-, Cos+ to Cos- ¹	4.2	4.7		kΩ
	Common-mode, to GND		2.2		kΩ
Resolution with interpolation	Software selectable, for one sine/cosine period	2		10	bits
Frequency	Sin-Cos interpolation	0		450	kHz
	Quadrature, no interpolation	0		10	MHz
ESD protection	Human body model	±1			kV
Analog 0...5V Inputs (REF, FDBK)		Min.	Typ.	Max.	Units
Input voltage	Operational range	0		5	V
	Absolute maximum values, continuous	-12		+18	
	Absolute maximum, surge (duration ≤ 1s) [†]			±36	
Input impedance	To GND		27		kΩ
Resolution			12		bits
Integral linearity				±2	bits
Offset error			±2	±10	bits
Gain error			±1%	±3%	% FS ²
Bandwidth (-3Db)	Software selectable	0		1.1	kHz
ESD protection	Human body model	±5			kV
Safe Torque OFF (STO1+; STO1-; STO2+; STO2-)		Min.	Typ.	Max.	Units
Safety function	According to EN61800-5-2	STO (Safe Torque OFF)			
EN 61800-5-1/ -2 and EN 61508-5-3/ -4 Classification	Safety Integrity Level	safety integrity level 3 (SIL3)			
	PFHd (Probability of Failures per Hour - dangerous)	8*10 ⁻¹⁰		hour ⁻¹ (0.8 FIT)	
EN13849-1 Classification	Performance Level	Cat3/PLe			
	MTTFd (mean time to dangerous failure)	377		years	
Mode compliance		PNP			
Default state	Input floating (wiring disconnected)	Logic LOW			
Input voltage	Logic "LOW" (PWM operation disabled)	-20		5.6	V
	Logic "HIGH" (PWM operation enabled)	18		36	
	Absolute maximum, continuous	-20		+40	
Input current	Logic "LOW", pulled to GND		0		mA
	Logic "HIGH", pulled to +Vlog		5	13	
Pulse duration	Ignored high-low-high			5	ms
	Accepted pulse			20	
PWM operation delay	From Enabled low-high transition to PWM operation enabled			30	ms
ESD protection	Human body model	±2			kV
CAN-Bus		Min.	Typ.	Max.	Units
Compliance		ISO11898, CiA-301v4.2 & 402v3.0			
Bit rate	Software selectable	125		1000	Kbps
Bus length	1Mbps			25	m
	500Kbps			100	
	≤ 250Kbps			250	
Resistor	Between CAN-Hi, CAN-Lo by hardware through SW1	none on-board			
Node addressing	by software using EasySetUp or EasyMotion Studio	1-255			
ESD protection	Human body model	±15			kV
Conformity		Min.	Typ.	Max.	Units
EU Declaration	2014/30/EU (EMC), 2014/35/EU (LVD), 2011/65/EU (RoHS), 1907/2006/EC (REACH), 93/68/EEC (CE Marking Directive), EC 428/2009 (non dual-use item, output frequency limited to 590Hz)				

[†] Stresses beyond values listed under "absolute maximum ratings" may cause permanent damage to the device. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

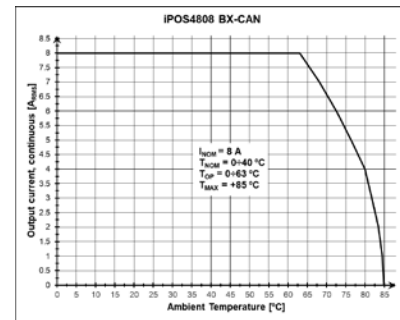


Figure 1. iPOS4808 BX-CAN De-rating with ambient temperature³

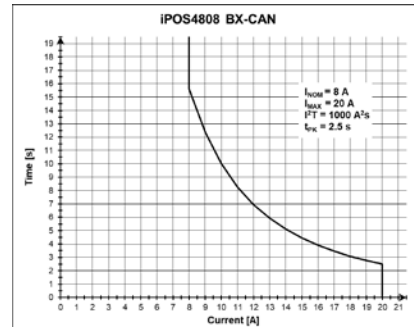


Figure 2. iPOS4808 BX-CAN Over-current diagram³

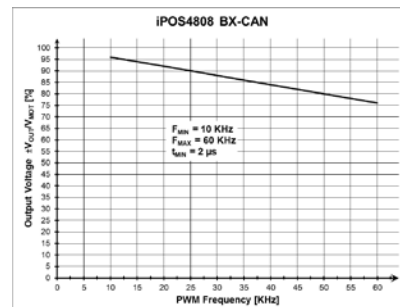


Figure 3. iPOS4808 BX-CAN Output Voltage De-rating with PWM frequency³

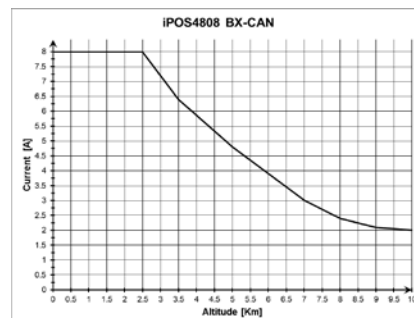


Figure 4. iPOS4808 BX-CAN De-rating with altitude³

¹ For many applications, a 120Ω termination resistor should be connected across SIN+ to SIN-, and across COS+ to COS- (set SW2 switches 3 and 4 to ON). Please consult the feedback device datasheet for confirmation.

² "FS" stands for "Full Scale"

³ Measured under the following conditions: BLDC; Vmot=48V, Vlog=24V, PWM=20kHz

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		Title of document	N° document	
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