

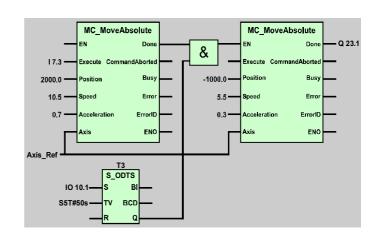
TML_LIB_S7 - MOTION CONTROL LIBRARY FOR SIMATIC S7- 300/400 EMBED TECHNOSOFT DRIVES INTELLIGENCE ON SIEMENS PLC ENVIRONMENT

Technology is moving fast and timeto-market window narrows. To capitalise on the power of embedded intelligence in Technosoft Drives and on the extreme flexibility of Technosoft Motion Language (TML), Technosoft introduces the TML_LIB libraries for its Intelligent Servo Drives and Motors family.

TML_LIB_S7 is a collection of functions and function blocks that allow you to implement motion control applications on a Siemens PLC, in order to run our MotionChip technology-based Intelligent Drives.

The library allows you to focus on the main aspects related to your specific application, and to easily use the drive and execute motion commands, by calling appropiate functions from the library. Its components are built using the guidelines described in the IEC 61131 standards. Beside the functions presented in this standard, the library also contains functions which implement specific features found on our drives.

The powerful motion control features of Technosoft Intelligent Drives/ Motors are based on their high-level progammability in Technosoft Motion Language, a common programming platform for all these drives. TML_LIB_S7 offers you access to TML functionality, without the need to use the TML commands. To some extent, TML LIB S7 as compared to TML is similar to programming in high-level languages, as compared to the assembly language.



FEATURES

- Function blocks interface and functionality complying to the IEC 61131 standard
- Supports new motion modes and features of Tehnosoft Drives/Motors
- Easy to embed in existing Step7 projects
- * Works with Simatic S7-300 and Simatic S7-400 PLCs
- * Can control all Technosoft Drives/Motors via CAN interface

HARDWARE REQUIREMENTS

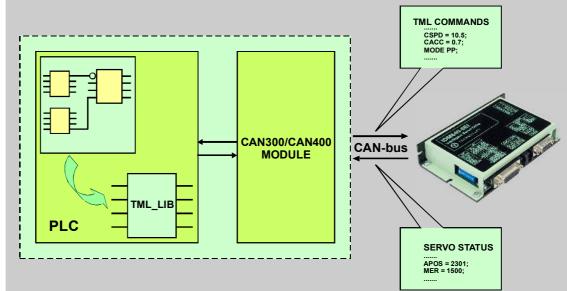
In order to use TML_LIB_S7 you must have the following minimal hardware configuration:

- One or more Technosoft Intelligent Drives/Motors connected through a CAN-bus
- A Siemens SIMATIC S7-300/S7-400 PLC to control Technosoft Drives/Motors
- A CAN300/CAN400 module from Systeme Helmholz to interface the PLC with the CAN-bus network

SOFTWARE REQUIREMENTS

The software required for implementing an application in the previous configuration consists of:

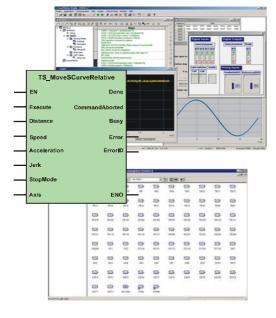
- TML_LIB_S7 library for the control of Technosoft Drives/ Motors from Siemens PLC
- EasyMotion Studio for configuration and tuning of Intelligent Drives/Motors
- Siemens Simatic Step7 V5.1+SP6 for PLC hardware configuration and programming
- CANparam from Systeme Helmholz to configure the CAN300/ CAN400 module





TML_LIB_S7 FUNCTION BLOCKS

	Function block	Descriptions
	MC_MoveAbsolute	Commands an absolute positioning w ith trapezoidal speed profile to the selected axis
	MC_MoveRelative	Commands a relative positioning with trapezoidal speed profile to the selected axis
	TS_MoveSCurveAbsolute	Commands an absolute positioning with an S-curve profile for speed, and with trapezoidal profile for acceleration
	TS_MoveSCurveRelative	Commands a relative positioning with an S-curve profile for speed, and with trapezoidal profile for acceleration
	TS_MoveVelocity	Commands a trapezoidal speed profile to the selected axis
Motion	TS_MovePVT	Sets the motion mode PVT and sends PVT points to the selected axis
	TS_ExternalAnalogue	Enables the drive on selected axis to use external analogue reference
	TS_ExternalDigital	Enables the drive on selected axis to use external digital reference when position control is performed
	TS_ExternalOnLine	Enables the drive on selected axis to use external reference received via a communication channel
	MC_GearIn	Configures and activates electronic gearing mode between Technosoft drives
	MC_GearOut	Disengages the slave axis from master axis in electronic gearing mode
	TS_CamIn	Configures and activates electronic camming mode between Technosoft drives
	M C_Cam Out	Disengages the slave axis from master axis in electronic camming
	MC_STOP	Commands a stop motion to the selected drive
	TS_AxisInit	Initializes drive's parameters for messages sent automatically by the drive
Administrative	MC_POWER	Enables/disables the pow er stage of the drive on the selected axis
	MC_ReadStatus	Returns the axis state
	MC_ReadActualPosition	Requests the actual position from the selected axis and returns the value of actual position
	TS_WriteLongParameter	Writes a long-type value in the specified location on the selected axis
	TS_WriteFixedParameter	Writes a fixed-type value in the specified location on the selected axis
	TS_WriteIntegerParameter	Writes an integer-type value in the specified location on the selected axis
Adn	TS_ReadLongParameter	Reads the value a long-type variable from the selected axis
	TS_ReadFixedParameter	Reads the value a fixed-type variable from the selected axis
	TS_ReadIntegerParameter	Reads the value an integer-type variable from the selected axis
	M C_Cam Table Select	Selects the active cam table for electronic camming
Comm	TS_MessageBuilder	Receives data from function blocks and builds the CAN message
	TS_MessageInterpreter	Interprets and saves data from received messages for each axis



Ordering Information				
P034.001.E002	EasyMotion Studio software			
P040.001.E301	TML_LIB_S7 for Siemens SIMATIC S7			

TECHNOSOFT PRODUCTS

Intelligent Servo Drives / Motors compatible with TML_LIB_S7

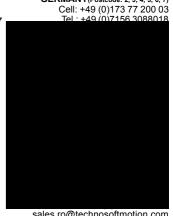
IPS110	Microstep / DC Drive, 45V, 0.5A, CAN
PIM2401	Plug-in Control Module, 24V, 1A, CAN
PIM2403	Plug-in Control Module, 24V, 3A, CAN
ISCMxx05	Servo Modules, 48/80V, 5A, CAN
IPS210	Microstep / DC Drive, 24V, 0.5A, CAN
ISM4803	Servo Control Module, 48V, 3A, CAN
ISCMxx05	Servo Modules, 48/80V, 5A, DIN, CAN
IBL2401	Servo / Stepper Drive, 24V, 1A, CAN
IBL2403	Servo / Stepper Drive, 24V, 3A, CAN
IBL3605	Servo / Stepper Drive, 36V, 5A, CAN
IDM240	Servo / Stepper Drive, 48V, 5A, CAN
IDM640	Servo / Stepper Drive, 80V, 8A, CAN
IDM680	Servo / Stepper Drive, 80V, 8A, CAN
IDM3000	Servo / Stepper Drive, 325V, 10A, CAN
IM23x	Servo Motors Size 23, 0.1-0.3Nm, CAN
IS23x	Step Motors Size 23, 0.5-1.8Nm, CAN

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